

Design of PSO Based KY Boost Converter to Reduce Output Ripple Voltage

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Abstract:

The main objective of this paper is to reduce the output ripple voltage and settling time of KY Boost converter. This converter operates under continuous transmission form with small output volt swell in the sequence of few mV, quick transient response and settling time gaining larger voltage conversion ratio. In this paper, particle swarm optimization algorithm (PSO) tuned PI controller is proposed to reduce the output ripple voltage further and achieve rapid settling time when compared to the PI and PID controllers. The simulated results are executed in MATLAB/SIMULINK showing that there is a considerable reduction in output voltage ripple in the order of mV along with quick settling time as compared to the existing system.

Keywords: Boost converter, KY converter, Output Voltage Ripple, Particle Swarm Optimization (PSO), PI controller.

I.INTRODUCTION

For the betterment of computing and communication devices such as Analog circuit, Personal Digital Assistant (PDA), MP3 player, Bluetooth devices, amplifier etc., it is necessary to boost up the output voltage for fixed input voltage. In such cases designer should concentrate on the output voltage ripple, settling time and transient response of the converter. In prevailing non-isolated step up DC - DC voltage converters leads to formation of large voltage ripples at output. In order to control this, the methods used are Equivalent Series Resistant (ESR) Capacitor [1], adding an inductance – capacitance (LC) filter [2]. Though these methods have good load transient response but it is difficult to achieve right-hand zero under Continuous Conduction Mode (CCM) [3]-[9] practically. The established control techniques for DC-DC converter are coupling inductors [3], voltage control techniques [4]–[9], sliding mode converter [10] and loop bandwidth control [11] for the reduction of output voltage ripples. It is clear that these systems [3]-[9] have one right - half plane zero with CCM which produces good transient response but achieving this in practice is difficult. In this paper, the output voltage ripple of the KY converter [13] is controlled based on Particle Swarm Optimisation techniques10. The parameter use for performance are estimated in time domain. The converter along with PSO tuning is represented in MATLAB simulink model and the results obtained from simulation evince that there is a reduction in output voltage ripple with quick settling time compared to existing system.

II.PROPOSED SYSTEM

In this proposed system particle swarm optimization algorithm [11] is implemented in the controller to select the firing angle of KY converter switches in order to reduce the output voltage ripple which is represented by the block diagram in following figure 1. The main blocks of proposed system consist of KY converter, comparator, PWM generator, controller tuned by particle swarm optimization (PSO) algorithm. The comparator compares the output voltage (V₀) with the reference signal voltage (V_{ref}) and generates an error signal (e). The error signal is fed into PSO based controller and the output of the controller is a duty cycle (d) which is fed into the PWM generator to produce the switching pulse which drives the converter. The main blocks of proposed system consist of KY converter, comparator, PWM generator, controller tuned by particle swarm optimization (PSO) algorithm. The comparator compares the output voltage (V₀) with the reference signal voltage (V_{ref}) and generates an error signal (e) . the error signal is fed into PSO based PI controller and the output of the controller is a duty cycle(d) which is fed into the PWM generator to produce the switching pulse which drives the converter. A.Circuit description.The positive output KY converter [4]-[5] shown in the following fig.1. This circuit is a combination of KY converter and SR boost converter which operates in two modes based on the switching sequence.

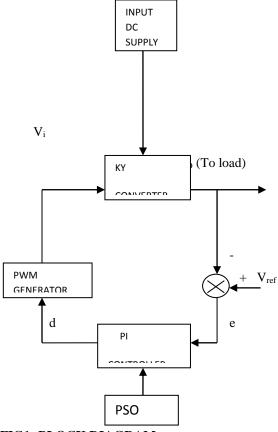


FIG1: BLOCK DIAGRAM

III.BASIC OPERATION OF POSITIVE OUTPUT KY BOOST CONVERTER

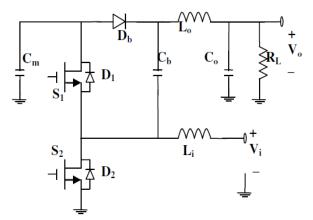


Fig2+ve BOOST CONVERTER

The KY converter consists of two switches S_1 and S_2 with protective diode D_1 and D_2 respectively, one capacitor C_b

for transferring energy , one output inductor Lo, and one output Capacitor C_0 , and one buffer capacitor Cm. It has inductance at both input and output side so output current ripple is low which tends to low output voltage ripple around 200mv. It is a non- isolated converter works in continues conduction mode with conversion voltage ratio of 1plus d, where d is a duty cycle of the controller. Based on the mode of operation the firing pulse of the corresponding switches was given by the PSO based controller with response to the error signal.

B. Modes of operation

KY converters has two modes of operation based on switching sequence

Mode 1: As soon as the switch s_1 turned OFF and s_2 turned ON, the capacitor C_m discharged and the capacitor C_b is charged the voltage across L_i is V_I there by L_I is magnetized and Lo is demagnetized, the current flows through the L_O is the difference between the current through C_m and current through R_L , the current through C_O is the different between current through L_O and current through R_L and the current through capacitor C_m is the sum of current through energy transfer capacitor C_b output inductor L_O which is represented in differential equation (1)

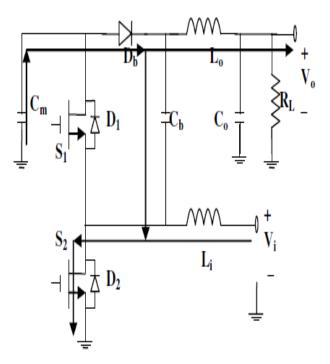


Fig 3: MODE 1 OPERATION

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(1) Mode

$$\begin{cases} Li \frac{\partial iLi}{\partial t} = vi, \\ Lo \frac{\partial iLo}{\partial t} = vcm - vo, \\ Co \frac{\partial vo}{\partial t} = iLo - \frac{vo}{RL}, \\ Cm \frac{\partial vcm}{\partial t} = -icb - iLo. \end{cases}$$

2: when the switch S_1 turned OFF and S_2 turned ON the capacitor C_b is discharged and the capacitor C_m is charged and voltage across L_i is calculated by the difference between V_I and V_{cm} , thereby magnetizing Lo and L_i is demagnetized. The voltage across L_0 is the difference between voltage $2V_{cm}$ and V_0 . The current through C_0 is the difference between current through L_0 and current through R_L , and the current through capacitor C_m is the difference between the current through output inductor L_0 and input inductor L_i respectively which is represented in differential equation (2).

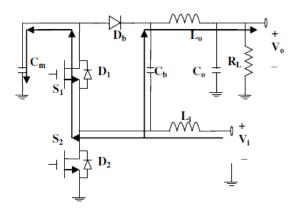


Fig 4: MODE 2 OPERATION

$$\begin{cases}
Li \frac{\partial iLi}{\partial t} = vi - v_{Cm}, \\
Lo \frac{\partial iLo}{\partial t} = 2v_{Cm} - v_{O}, \\
Co \frac{\partial v_{O}}{\partial t} = iLo - \frac{v_{O}}{RL}, \\
Cm \frac{\partial v_{Cm}}{\partial t} = iLi - iLo.
\end{cases}$$
(2)

From equation (3), we can obtain the average value of voltage and current, which is represent as x

$$\left\langle x\right\rangle = \frac{1}{T_s} \int_{0}^{T_s} x d\tau \; .$$

The average inductance and capcitor from equation (1)-(3) represented in equation (4):

$$\begin{cases} Li \frac{\partial \langle iLi \rangle}{\partial t} = \langle vi \rangle - (1-d) \langle vcm \rangle, \\ Lo \frac{\partial \langle iLo \rangle}{\partial t} = (2-d) \langle vcm \rangle - \langle vo \rangle, \\ Co \frac{\partial \langle vo \rangle}{\partial t} = \langle iLo \rangle - \frac{\langle vo \rangle}{RL}, \\ Cm \frac{\partial \langle vcm \rangle}{\partial t} = -\langle iLo \rangle + (1-d) \langle iLi \rangle - d \langle icb \rangle, \end{cases}$$

$$(4)$$

where d is the duty cycle of PWM generator. The voltage conversion ratio can be obtained by following equation (5). $V_0/V_i=2-d/1-d$ (5)

The specification of KY boost converter is given in following TABLE1.

Parameter	Symbol	Value	Unit	
Input voltage	Vi	12	V	
Rated output voltage	\mathbf{V}_0	36	V	
Rated load current	I ₀	2.5	А	
Buffer capacitance	C _m	1000	μF	
Output capacitor	C_0	470	μF	
Output and input inductor	L ₀ ,L _i	15	μН	
Energy transfer capacitor	C _b	680	μF	
Output capacitor	C_0	470	μF	
Load resistor	R _L	14.4	Ω	
Switching frequency	Fs	195	kHz	

TABLE I. SPECIFICATIONS OF KY BOOST CONVERTER

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(3)

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IV.PARTICLE SWARM OPTIMIZATION

In recent years, the research community is paying more attention towards PSO for research purposes. It is initially proposed by James Kennedy and Russell Eberhart in 1995. It uses a number of particles that makes a swarm to move in the search space for finding the best solution. Each particle is constantly searching for the optimum solution which has a velocity because of the movement of particle and remembers its own personal best position as well as the neighbour's best position. The particles in the swarm co-operate each other and exchange their information about what they've discovered in the places they have searched. A particle finds the finesses of those in its neighbourhood and uses the position of the particle with best fitness. This position leads to adjust the particle's velocity. To get the new particle's velocity, the following calculation is used. New particle velocity = current velocity + weighted random portion in the direction of its personal best + weighted random portion in the direction of the neighbourhood best. There are two types of neighbours. They are, 1. Geographical neighbours 2. Social neighbours

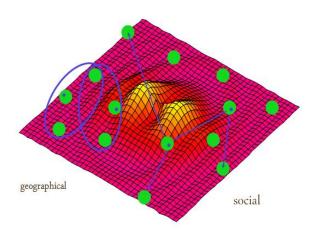
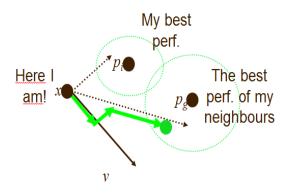


FIG 5:Neighbourhoods

Particles tune their positions according to a ``Psychosocial compromise'' among what an person is relaxing by means of, and what will society expect. Each particle tries to modify its position with the follow in sequence:

- the present position,
- the present velocity,
- the distance between the current position and pbest,
- the detachment among the current spot and the finest.

• The modification of the particle's position can be scientifically model according the following equation (6)



 $V_i^{k+1} = wV_i^k + c_1 \operatorname{rand}_1(\ldots) x (\operatorname{pbest}_i - s_i^k) + c_1 \operatorname{r$

$$c_2 \operatorname{rand}_2(...) x (gbest-s_i^k) (6)$$

where,

$v_i^{\ k}$:		velocity	of	agent	i	at	iteration	k,
	w:				V	ve	ight	tingfuncti	on,
	c _j :					١	vei	ghtingfact	or,
	rand	:	:	regularly		sį	orea	nd cas	ual
numeral among 0 and 1									

s_i^k: current position of agent i at

iteration							
pbest _i	:	р	best	of	mediator	i,	
gbest:	gbest	of the	e cluster.				

In this proposed system particle swarm optimization (**PSO**) algorithm is used to tune the **PI** controller in order to reduce the output voltge ripple of KY converter. The output voltage is compared with the reference signal, the generated error signal is injected to **PSO** tuned PI controller. **PSO** algorithm is used to select the optimized K_{P,K_I} value and this gives corresponding dutycycle[d] at the output side of the controller.The dutycycle[d] is fed into PWM generator working at the frequency of 195 KHZ ,the output of the PWM generator is the firing angle given to the swithches of the KY converter.

V.SIMULATION RESULT:

The MATLAB SIMULINK for the proposed KY converter was shown in the figure from 6 to 8.



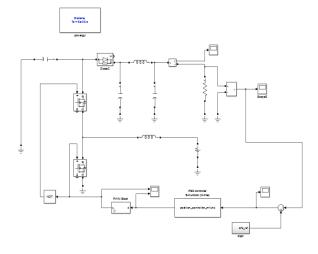
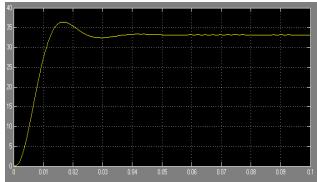


Fig 6: SIMULINK MODEL OF PROPOSED PSO BASED KY CONVERTER



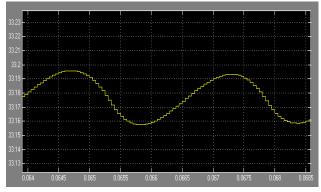


Fig 8:output voltage ripple waveform of PSO based KY boost converter

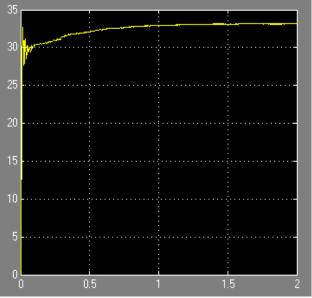


Fig 7: Output Voltage Waveform Of PI controlled KY boost Converter

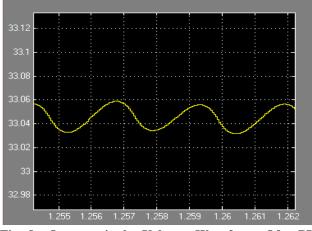


Fig 8: Output ripple Voltage Waveform Of PI controlled KY boost Converter

Simulation was performed for both PI controlled KY boost converter and PSO tuned PI controlled KY converter. When compared to the existing system, PARTICLE SWARM OPTIMIZATION (PSO) tuned PI controller works more efficient then PI and PID controllers.

VI. CONCLUSION

By using PSO tuned PI controlled KY Boost Converter, the output voltage ripple and settling time is reduced when compared to the existing PI and PID controllers.



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